

- Kapitza pendulum using FM expansion:

$$H(t) = \frac{p_\theta^2}{2m} - m(\omega_0^2 + A \cos \omega t) \cos \theta$$

$$= H_{kin} + H_{pot} + \omega f(t) H_{drive}$$

• where $H_{kin} = p_\theta^2 / 2m$

$$H_{pot} = -m\omega_0^2 \cos \theta$$

$$H_{drive} = -m \cos \theta, \quad f(t) = A \cos \omega t$$

→ plug in expressions: for $\tau := \omega t$

$$H^{(0)} = \frac{1}{2\pi} \int_0^{2\pi} d\tau H(\tau) = H_{kin} + H_{pot}$$

$$H^{(1)} \equiv 0, \quad \text{since } f(\tau) = f(2\pi - \tau)$$

$$H^{(2)} = \frac{\omega}{12\pi \omega^2} [H_{kin}, [H_{kin}, H_{drive}]] \times$$

$$\times \int_0^{2\pi} d\tau_1 \int_0^{\tau_1} d\tau_2 \int_0^{\tau_2} d\tau_3 \quad 2f(\tau_2) - f(\tau_1) - f(\tau_3)$$

$\approx \mathcal{O}(1/\omega) \rightarrow$ suppressed, drop

$$- \frac{\omega^2}{12\pi \omega^2} [H_{drive}, [H_{drive}, H_{kin}]]$$

$$\times \int_0^{2\pi} d\tau \int_0^{\tau_1} d\tau_2 \int_0^{\tau_2} d\tau_3 \quad f(\tau_2)f(\tau_3) + f(\tau_2)f(\tau_1) - 2f(\tau_1)f(\tau_3)$$

$\approx \mathcal{O}(1)$

- can show: using $[p_\theta, f(\theta)] = -i \partial_\theta f(\theta)$

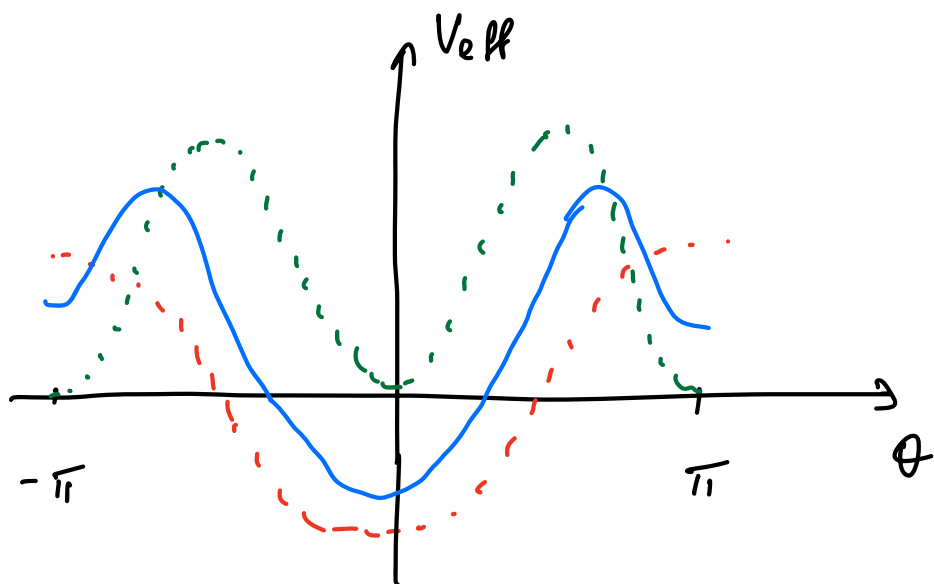
$$1) [H_{drive}, [H_{drive}, H_{kin}]] = \frac{1}{m} \left(\frac{\partial H_{drive}}{\partial \theta} \right)^2$$

$$2) \frac{1}{(2\pi)^3} \int_0^{2\pi} d\tau_1 \int_0^{\tau_1} d\tau_2 \int_0^{\tau_2} d\tau_3 (f(\tau_2)f(\tau_3) + f(\tau_2)f(\tau_1) - 2f(\tau_1)f(\tau_3)) = \frac{A^2}{4}$$

$$\Rightarrow H_F^{(0)} = H_{kin} + H_{rot} + \frac{A^2 m}{4} \frac{(\partial_\theta H_{drive})^2}{= \sin^2 \theta}$$

$$= \frac{p_\pm^2}{2m} - m\omega_0^2 \cos \theta + \frac{A^2 m}{4} \sin^2 \theta$$

$=: V_{eff}(\theta)$ effective potential



$$\propto \cos \theta$$

$$\propto \sin^2 \theta$$

$$\propto -\cos^2 \theta + \sin^2 \theta$$

$$\partial_\theta^2 V_{eff}(\theta) = m\omega_0^2 \cos \theta + \frac{A^2 m}{2} \cos 2\theta$$

$$\theta = \pi \quad = -m\omega_0^2 + \frac{A^2 m}{2} \stackrel{!}{\geq} 0$$

dynamical stabilization

stable for $A > \sqrt{2} \omega_0$
at inverted equilibrium

- due to scaling of drive amplitude with frequency, need to be careful with power-counting!

→ limit $\omega \rightarrow \infty$ not just given by time-average
• are we missing any higher order terms?

a) n 'th order term contains n -nested commutators

b) & n -fold t -order integral $\propto 1/\omega^{n-1}$

to have a contrib. of $O(1)$, only nested commutator containing H_{int} precisely once (& H_{drive} $n-1$ times) survive:

$$[\dots [H_{\text{int}}, H_{\text{drive}}], H_{\text{drive}}, \dots, H_{\text{drive}}]$$

but: $H_{\text{int}} \sim \partial_\theta^2$, 3- & higher nested commutators vanish identically ✓

- is there a more efficient way to compute this?

→ ideally, so we can go to order $1/\omega$

→ Kapitza pendulum in rotating frame

$$H(t) = \frac{p_\theta^2}{2m} - m(\omega_0^2 + A\omega \cos \omega t) \cos \theta$$

recall:

"problematic" scaling,
messes up power counting!

$$H_{\text{rot}}(t) = V^\dagger(t) H(t) V(t) \quad \underbrace{-i V^\dagger \partial_t V(t)}$$

idea: use Galilean term
to cancel $\approx \omega$ term
by choosing $V(t)$ suitably

e.g. $V(t) = \exp\left(-i \int_0^t (\underbrace{m A \omega}_{\Delta(t)}) \cos \omega t \, dt \times \cos \Theta\right)$

$$\therefore \Delta(t) = -m A \sin \omega t$$

then: $i V^\dagger \partial_t V = -m A \omega \cos \omega t \cos \Theta = \omega f(t) H_{\text{drive}}$

compute:

$$V^\dagger H(t) V(t) = e^{-i \Delta \cos \Theta} (H_{\text{kin}} + H_{\text{pot}} + \omega f(t) H_{\text{drive}}) e^{+i \Delta \cos \Theta}$$

$$= e^{-i \Delta \cos \Theta} H_{\text{kin}} e^{+i \Delta \cos \Theta} + H_{\text{pot}} + \omega f(t) H_{\text{drive}}$$

$$e^{-i \Delta \cos \Theta} \frac{p^2}{2m} e^{+i \Delta \cos \Theta} = \frac{p^2}{2m} + \frac{\Delta^2(t)}{2m} \sin^2 \Theta + \frac{\Delta(t)}{2m} \{ \sin \Theta, p \}_+$$

$$\Rightarrow H_{\text{rot}}(t) = \frac{p^2}{2m} - m \omega_0^2 \cos \Theta + \frac{\Delta^2(t)}{2m} \sin^2 \Theta + \frac{\Delta(t)}{2m} \{ \sin \Theta, p \}_+$$

since $\Delta \approx \mathcal{O}(\omega^2)$,

$$H_F^{(0)} = \frac{1}{T} \int_0^T dt H_{\text{rot}}(t)$$

$$= \frac{p^2}{2m} - m \omega_0^2 \cos \Theta + \frac{A^2 m}{4} \sin^2 \Theta \quad \checkmark$$

- can easily identify the correct $1/\omega$ corrections
- change of frame transformations lead to a resummation of IFE subseries
 - ↳ non-perturbative effects

⇒ scaling drive amplitude ω/ω can lead to interesting phenomena in the time-averaged $H_F^{(0)}$

— Floquet engineering :

Q: how should we choose the drive Hamiltonian so we can prescribe the properties of H_F ?

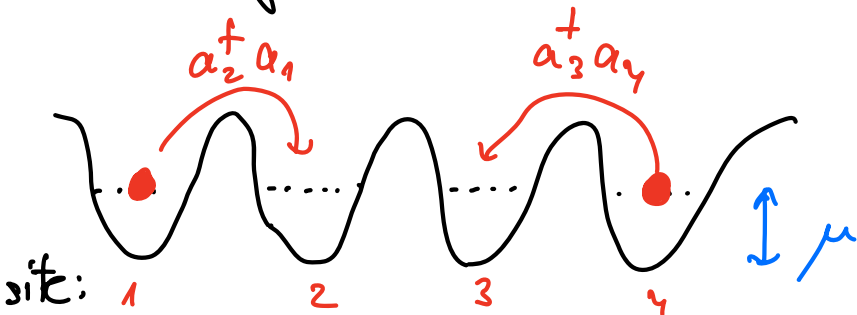
Example 1 : dynamical stabilization

- Kapitza oscillator (Piotr Kapitza, '51)
- Paul trap (Wolfgang Paul, Nobel prize '89)

Example 2 : dynamical localization :

→ free fermion/boson chain :

$$H_0 = \sum_j -J (a_{j+1}^\dagger a_j + \text{h.c.}) - \mu a_j^\dagger a_j$$

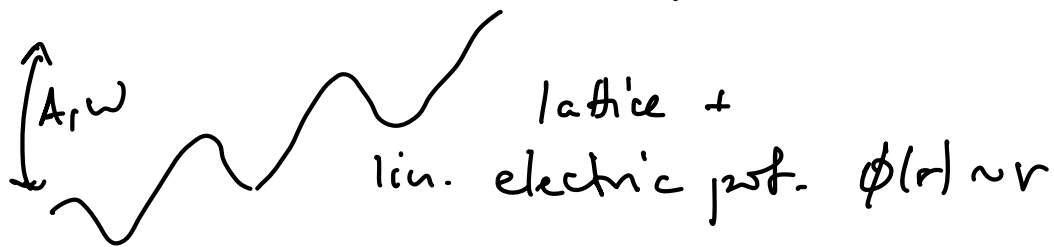


$$n_j = a_j^\dagger a_j \text{ density on site } j$$

hopping/tunneling delocalizes the wavefn (e.g. BEC, but also for fermions)

want: to localize particles, i.e. suppress tunneling J

$$H_{\text{drive}}(t) = A \omega \cos \omega t \sum_j j u_j \quad : \quad \begin{array}{l} \text{oscillating} \\ \text{electric potential} \end{array}$$



total Hamiltonian:

eliminate by
going to rot-frame

$$H_0 = \sum_j -J (a_{j+1}^\dagger a_j + \text{h.c.}) - \mu u_j + A \omega \cos \omega t \sum_j j u_j$$

$$V(t) = e^{-i A \sin \omega t \sum_j j u_j} = \prod_j e^{-i A \sin \omega t j u_j}$$

$$H_{\text{rot}}(t) = \sum_j -J V^\dagger(t) a_{j+1}^\dagger a_j V(t) + \text{h.c.} - \mu u_j$$

$$= \sum_j -J V^\dagger a_{j+1}^\dagger V V^\dagger a_j V + \text{h.c.} - \mu u_j$$

$$= \sum_j -J e^{+i A \sin \omega t (j+1) u_{j+1}} a_{j+1}^\dagger e^{-i A \sin \omega t (j+1) u_{j+1}}$$

$$\times e^{+i A \sin \omega t j u_j} a_j e^{-i A \sin \omega t j u_j} + \text{h.c.} - \mu u_j$$

need: $e^{i\alpha u} a e^{-i\alpha u} =: F(\alpha) (\neq)$; $\alpha := A j \sin \omega t$

$$\partial_\alpha F = e^{i\alpha u} \underbrace{i[n, a]}_{= -ia} e^{-i\alpha u} = -iF$$

$$\Rightarrow F(\alpha) = F(0) e^{-i\alpha} \stackrel{(\neq)}{=} a e^{-i\alpha}$$

$$\overline{H_{\text{int}}(t)} = \sum_j -J e^{+i A \sin \omega t (j+1)} a_{j+1}^\dagger e^{-i A \sin \omega t j} a_j + \text{h.c.} - \mu u_j$$

$$= \sum_j -J \left(e^{+i A \sin \omega t} a_{j+1}^\dagger a_j + \text{h.c.} \right) - \mu u_j$$

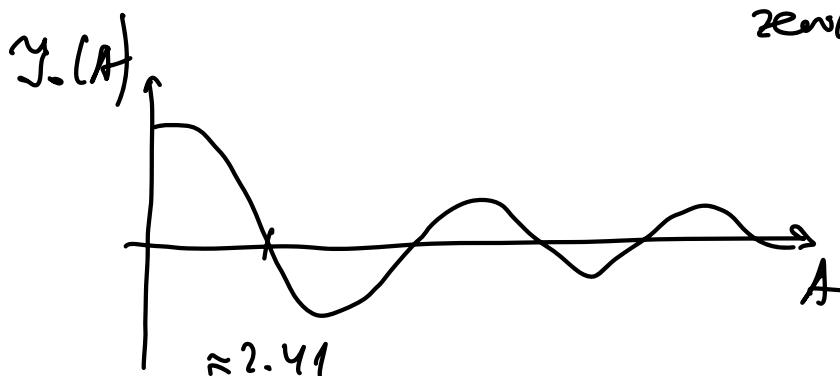
- apply IFE:

$$H_F^{(0)} = \frac{1}{T} \int_0^T dt H_{\text{int}}(t)$$

$$= \sum_j -J_{\text{eff}}(A) \left(a_{j+1}^\dagger a_j + \text{h.c.} \right) - \mu u_j$$

where $J_{\text{eff}}(A) = \frac{1}{T} \int_0^T dt e^{-i A \sin \omega t} = \tilde{J}_0(A)$

zeros Bessel fn of 1st kind

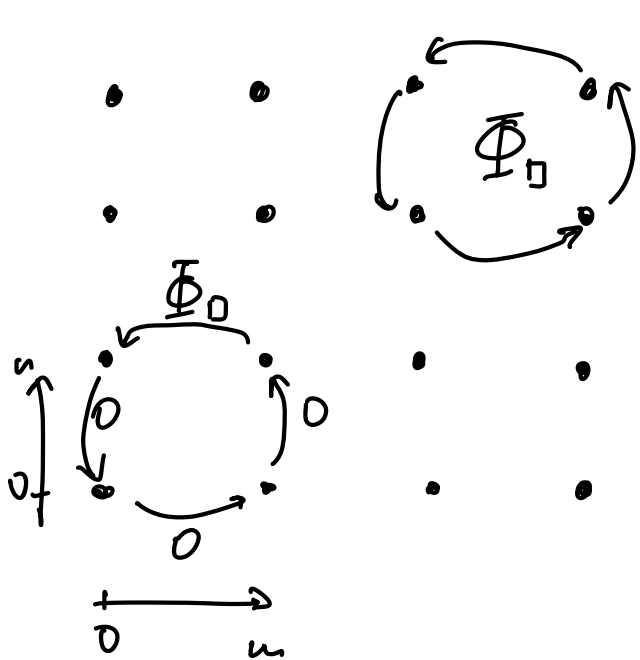


at $A \approx 2.41$ coherent
 $J_{\text{eff}}(A) \approx 0 \rightarrow$ hopping suppr.
dynamical localization

Example 3 : artificial magnetic fields

consider the Harper-Hofstadter Hamiltonian:

- 2D square lattice



$$H_{HH} = -K \sum_{m,n} e^{i\varphi_{mn}} a_{m+1,n}^\dagger a_{m,n} + \text{h.c.} \\ - J \sum_{m,n} a_{m,n+1}^\dagger a_{m,n} + \text{h.c.}$$

$$\varphi_{mn} = \Phi_0 (m+n)$$

$$n_{mn} = a_{mn}^\dagger a_{mn} : \text{particle op.}$$

- Φ_0 : magnetic flux per plaquette
- magnetic field breaks time-reversal symmetry (i.e. cannot gauge away either term)

- in materials: a_{mn} : electron operator

→ e^- are charged → couple to magnetic fields

issue: Φ_0 limited by strength of magnetic field
(↳ technical challenge)

- quantum simulators

• neutral "particles" → do not couple to EM fields!

idea: use Floquet engineering

$$H(t) = H_0 + H_{\text{drive}}(t)$$

$$H_0 = - \sum_{m,n} J_x a_{m+1,n}^\dagger a_{m,n} + J_y a_{m,n+1}^\dagger a_{m,n} + \text{h.c.}$$

$$H_{\text{drive}}(t) = \omega \sum_{m,n} \left[\frac{A}{2} \sin(\omega t - \varphi_{mn} + \frac{\Phi_D}{2}) + \mu \right] a_{m,n}^\dagger a_{m,n}$$

gradient along x-only

where $\varphi_{mn} = \Phi_D (m+n)$ spatially inhom phase of drive

→ breaks time-reversal

→ go to rotating frame using

$$V(t) = e^{-i \int_0^t dt' H_{\text{drive}}(t')} \text{ to eliminate } \omega\text{-term}$$

$$H_{\text{rot}}(t) = G(t) + G^\dagger(t)$$

$$G(t) = - \sum_{m,n} J_x e^{-i \sum_{\Phi} \sin(\omega t - \varphi_{mn}) + i \omega t} a_{m+1,n}^\dagger a_{m,n} + \text{h.c.}$$

$$+ J_y e^{-i \sum_{\Phi} \sin(\omega t - \varphi_{mn})} a_{m,n+1}^\dagger a_{m,n} + \text{h.c.}$$

$$\sum_{\Phi} = A \sin(\Phi_D/2)$$

- effective Hamiltonian:

$$\text{use } e^{i \alpha \sin(\omega t - \varphi)} = \sum_{\ell} J_{\ell}(\alpha) e^{-i \ell (\omega t - \varphi)}$$

$$\frac{1}{T} \int_0^T dt e^{-i \sum_{\Phi} \sin(\omega t - \varphi_{mn}) + i \omega t} =$$

$$= \sum_{\ell} J_{\ell}(\sum_{\Phi}) \underbrace{\int_0^T \frac{dt}{T} e^{-i \ell (\omega t - \varphi_{mn})} e^{i \omega t}}_{= e^{+i \varphi_{mn}} \delta_{\ell,1}} = J_1(\sum_{\Phi}) e^{i \varphi_{mn}}$$

$$H_F^{(0)} = - \sum_{m,n} \left(K e^{i\varphi_{m,n}} a_{m+1,n}^\dagger a_{m,n} + \text{h.c.} \right) \\ + \left(J a_{m,n+1}^\dagger a_{m,n} + \text{h.c.} \right)$$

where $K = J_x \vec{\sigma}_1(\vec{\sigma}_\Phi)$ & $J = J_y \vec{\sigma}_0(\vec{\sigma}_\Phi)$

→ HH Hamiltonian

artificial magnetic field

- Example 4: topological bands
(↪ project)

- Floquet engineering is limited by

- 1) laws of physics
- 2) your own creativity!

- remarks:

a) all of the above examples generalize to interacting systems (density-density interactions)

b) Floquet systems are intrinsically out of equil.

$$[H(t_1), H(t_2)] \neq 0$$

⇒ energy conservation lost

⇒ system can (and in general will) absorb energy from drive

↪ heating
• problematic for ordered states